Information Complexity and the Geometry of Communication

T.S. Jayram

IBM Almaden Research Center

December 19, 2009

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Communication





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Communication



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"Communication does not signify a problem newly discovered in our times, but a fashion of thinking and a method of analyzing which we apply in the statement of all fundamental problems."

Richard McKeon (1957)

Communication (CS Theory Version)

Multi-party Communication

- There are $t \ge 2$ players P_1, P_2, \ldots, P_t
- The input is a tuple (x_1, x_2, \ldots, x_t)
- P_i holds x_i (number-in-hand)
- The *protocol* specifies the rules for writing messages (on a blackboard)
- Players can use private random coins
- The message transcript depends on both the input and randomness



Quantify the *necessary* amount of communication needed to solve a communication problem.

Many ways to measure communication:

- Length of communication, i.e. #bits in the transcript
- Pounds of communication
- Symmetric communication

How much information about the inputs is contained in Π ?

- Alice's input is a set $x \subseteq [1..n]$
- Bob's input is a set $y \subseteq [1..n]$
- Communication problem: are the sets are disjoint?

$$\text{Disj}(x, y) = \bigvee_{j=1}^{n} (x_j \land y_j)$$

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L_{∞} estimation

- Inputs are $x, y \in \mathbb{R}^n$
- ℓ_{∞} norm $||a||_{\infty} = \max_{i} |a_{i}|$
- Threshold t, approximation $\alpha \ge 1$
- Is $||x y||_{\infty}$ at most t or greater than αt ?

$GapL_{\infty}$ and Dist

For each coordinate *j*:

$$|x_j - y_j| \le t \implies \text{Dist}(x_j, y_j) = 0, \text{ or}$$

$$|x_j - y_j| > \alpha t \implies \text{Dist}(x_j, y_j) = 1$$

$$\text{GapL}_{\infty}(x, y) = \bigvee_{j=1}^{n} \text{Dist}(x_j, y_j)$$

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Direct Sum

• Given two decision problems f and g:

$$f(x, y) = \bigvee_{j=1}^{n} g(x_j, y_j)$$

• Can we relate the communication complexity of f to that of g?

Direct Sum ls $CC(f) \ge n \cdot CC(g)$?

- Difficult to prove by directly analyzing the transcript
- Maybe information theory can help ...

Conditional Entropy: H(X | Y) is the *uncertainty* in *X* conditioned on *Y* Mutual Information: I(X : Y) = H(X) - H(X | Y) is the *reduction* in uncertainty of *X* when conditioned on *Y*

Conditional Mutual Information: I(X : Y | Z) = H(X | Z) - H(X | Y, Z)

Information Cost/Complexity

Definition

Let Π be the transcript of a *t*-player protocol on input x_1, x_2, \ldots, x_t .

The information cost of a protocol equals

 $I(X_1, X_2, ..., X_t : \Pi | D),$

where X_1, X_2, \ldots, X_t are jointly independent conditioned on D.

Information Complexity IC(f): the *minimum* information cost of a protocol that *correctly* computes f

[Chakrabarti, Shi, Wirth and Yao], [Bar-Yossef, Jayram, Kumar and Sivakumar]

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Theorem

Suppose f can be written as an OR of n disjoint instances of g. Then,

 $IC(f) \ge n \cdot IC(g).$

- Since CC(f) ≥ IC(f), we can prove lower bounds on CC(f) by proving lower bounds on IC(g).
- However, the support of the input distribution of g is on the O-instances of g!

Leads to interesting connections between information complexity and the geometry of communication.

Part II

Distance Estimation

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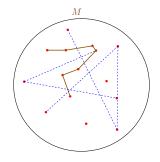
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Distance Estimation

A metric space M with distance function $d(\cdot, \cdot)$

- Alice holds $x \in M$; Bob holds $y \in M$
- Threshold *t*; approximation $\alpha \ge 1$
- Promise problem Dist:

No instance: $d(x, y) \le t$ (Close) Yes instance: $d(x, y) > \alpha t$ (Far)

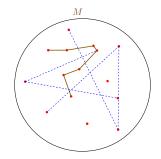


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No instance: $d(x, y) \le t$ (Close) Yes instance: $d(x, y) > \alpha t$ (Far)



Goal

Prove a lower bound on the information complexity of Dist

Notation: Let $\|\cdot\| = \frac{1}{2} \|\cdot\|^2$.

Let ρ be an embedding of M into Euclidean space ℓ_2

- Suppose $d(x, y) = \|\rho(x) \rho(y)\|$, for all $x, y \in M$ (Isometry)
- ullet Then, ho separates the close and far instances of Dist
- How does one show that such an embedding does not exist?

Poincaré-Type Inequalities

Definition (Poincaré Inequality)

- distribution η_0 on close instances
- 2 distribution η_1 on far instances
- **③** parameter λ

A Poincaré inequality holds for Dist if for all $\rho: M \rightarrow \ell_2$:

$$\mathbb{E}_{(x,y)\sim\eta_0}\|\rho(x)-\rho(y)\| \ge \lambda \cdot \mathbb{E}_{(x,y)\sim\eta_1}\|\rho(x)-\rho(y)\|$$

- $\lambda \ge 1/\alpha \implies$ no isometric embeddings exist
- 2) with larger λ , can also consider embeddings with distortion
- \odot with smaller λ , we can still say something interesting!

• Let
$$\eta_0 =$$
 unif. distrib. on $\{0, 1, ..., m-1\}$.

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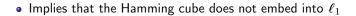
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• Let $\eta_0 = \text{unif. distrib. on } \{0, 1, ..., m-1\}.$ $\mathbb{E}_{x \sim \eta_0} \| \rho(x) - \rho(x+1) \| \ge \frac{1}{m} \cdot \| \rho(0) - \rho(m) \|$

- **2** Hamming cube $\{0,1\}^d$:
- η_0/η_1 = unif. distrib. on the edges/diagonals

 $\mathbb{E}_{(x,y)\sim\eta_0}\|\rho(x)-\rho(y)\|\geq \frac{1}{d}\cdot\mathbb{E}_{(x,y)\sim\eta_1}\|\rho(x)-\rho(y)\|$





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- $\bullet\,$ Implies that the Hamming cube does not embed into ℓ_1
- [Andoni,Krauthgamer] proved a Poincaré inequality for edit distance and used it to prove communication vs. approximation tradeoff.

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- $\bullet\,$ Implies that the Hamming cube does not embed into ℓ_1
- [Andoni,Krauthgamer] proved a Poincaré inequality for edit distance and used it to prove communication vs. approximation tradeoff.
- **(a)** Expanders: Poincaré inequality with $\lambda =$ normalized spectral gap.

Theorem ([Andoni, Jayram and Patrascu]) Suppose Dist satisfies a Poincaré inequality w.r.t. distributions η_0 , η_1 , and parameter λ . Then, $IC(Dist) \ge \frac{\lambda}{8}$

- [Bar-Yossef, Jayram, Kumar and Sivakumar] proved this result for $M = \mathbb{R}$.
 - $\bullet\,$ Yields space lower bounds for estimating ℓ_∞ in a data stream

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- [Bar-Yossef, Jayram, Kumar and Sivakumar] proved this result for M = ℝ.
 Yields space lower bounds for estimating ℓ_∞ in a data stream
- [Jayram and Woodruff] proved this result for the Hamming cube
 Yields space lower bounds estimating cascaded norms L_k

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 Yields space lower bounds estimating cascaded norms L_k
 L_k
- Our result implies improved lower bounds for sketching edit distance: $\Omega(\log \log d) \Longrightarrow \Omega(\log d).$

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Input Distribution

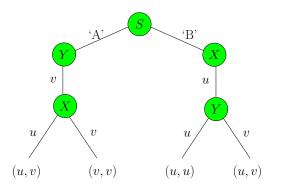
- **1** Define (X, Y, D) such that X and Y are independent conditioned on D
- 2 $\operatorname{Dist}(X, Y) = 0$

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Input Distribution

Define (X, Y, D) such that X and Y are independent conditioned on D
Dist(X, Y) = 0

$$D = (S,T) \qquad T = (u,v) \sim \eta_0$$



Transcript Wave Function

Let $\pi(x, y) = \text{prob.}$ distrib. over transcripts on a fixed input (x, y)

- $\pi(x, y)_{\tau}$ = prob. that the transcript equals τ
- $\pi(x, y)$ belongs to the unit simplex

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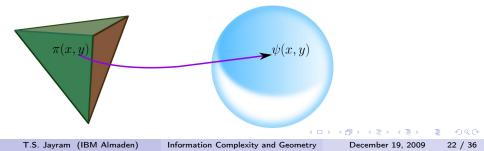
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Definition (Transcript wave function $\psi(x, y)$)

- $\psi(x, y)_{\tau} = \sqrt{\pi(x, y)_{\tau}} \quad \forall \tau.$
- $\psi(x, y)$ belongs to the *positive orthant* of the *unit sphere*



Definition (Hellinger Distance)

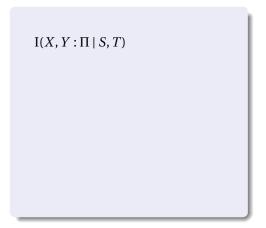
The square of the Hellinger distance between two transcript wave functions $\psi(x, y)$ and $\psi(x', y')$ is defined as $\|\psi(x, y) - \psi(x', y')\|$.

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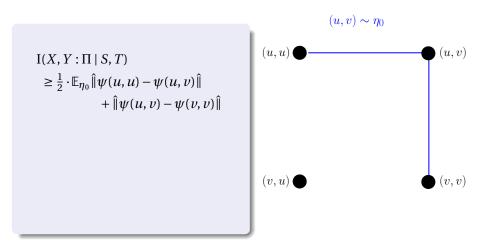
Proposition (Information Cost to Hellinger distance)

 $I(X, Y: \Pi \mid D) \ge \frac{1}{2} \cdot \mathbb{E}_{(u,v) \sim \eta_0} \| \psi(u,u) - \psi(u,v) \| + \| \psi(u,v) - \psi(v,v) \|$



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(Information Cost to Hellinger distance)

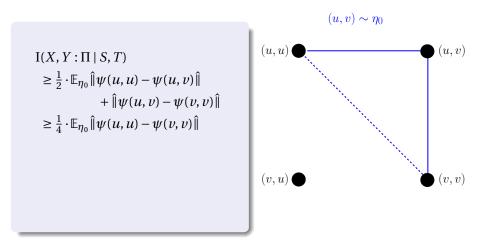
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24 / 36



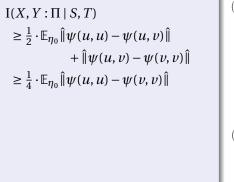
(Cauchy-Schwartz + Triangle Inequality)

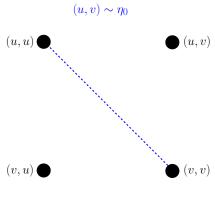
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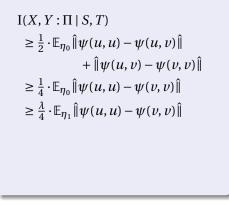
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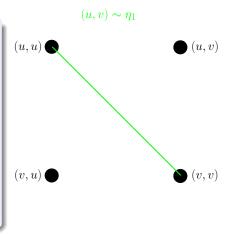
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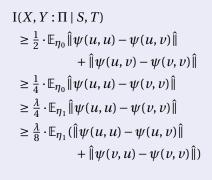
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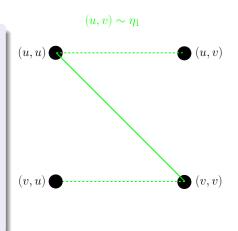




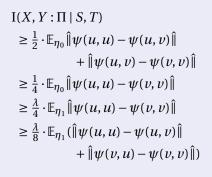
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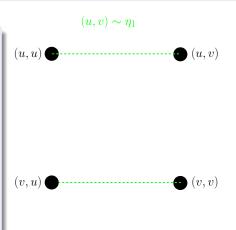
(Poincaré inequality: $\rho(u) = \psi(u, u)$)





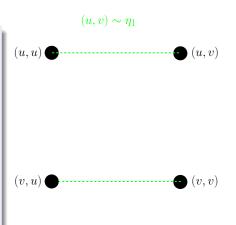
(Pythogorean Property of Communication Protocols [BJKS])





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$$\begin{split} \mathrm{I}(X,Y:\Pi \mid S,T) \\ &\geq \frac{1}{2} \cdot \mathbb{E}_{\eta_0} \left\| \psi(u,u) - \psi(u,v) \right\| \\ &\quad + \left\| \psi(u,v) - \psi(v,v) \right\| \\ &\geq \frac{1}{4} \cdot \mathbb{E}_{\eta_0} \left\| \psi(u,u) - \psi(v,v) \right\| \\ &\geq \frac{\lambda}{4} \cdot \mathbb{E}_{\eta_1} \left\| \psi(u,u) - \psi(v,v) \right\| \\ &\geq \frac{\lambda}{8} \cdot \mathbb{E}_{\eta_1} (\left\| \psi(u,u) - \psi(v,v) \right\| \\ &\quad + \left\| \psi(v,u) - \psi(v,v) \right\|) \\ &\geq \frac{\lambda}{8} \end{split}$$



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(Soundness)

Part III

The And problem

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The *t*-party And problem



- Player P_i holds a *single* bit x_i , i = 1..t
- Promise:

Yes instance: *every* player's bit is set to 1 No instance: *at most one* player's bit is set to 1

- Introduced in [Bar-Yossef, Jayram, Kumar and Sivakumar]
 - For proving multi-party set disjointness [Alon, Matias, and Szegedy] lower bounds via a direct-sum theorem
 - Yields space lower bounds for frequency moments in data streams

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- [BJKS] proved a lower bound of $\Omega(1/t^2)$
 - Improved to $\Omega(1/t^{1+\varepsilon})$, for any $\varepsilon > 0$, for one round communication

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 - Improved to $\Omega(1/t^{1+\varepsilon})$, for any $\varepsilon > 0$, for one round communication
- [Chakrabarti, Khot, and Sun] gave a $\Omega(1/(t \log t))$ bound for general communication and a $\Omega(1/t)$ bound for 1-round communication

Theorem ([Gronemeier])

The information complexity of And for general communication is $\Omega(1/t)$.

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Conditioning: Choose index D uniformly from [1...t].

Input: O Choose X_D uniformly from $\{0, 1\}$ O Set $X_j = 0$ for all $j \neq D$

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1 X_1, X_2, \dots, X_t are jointly independent conditioned on D

 $X_1 \wedge X_2 \wedge \dots \wedge X_t = 0$

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Information Cost to Hellinger distance:

$$I(X_1, X_2, ..., X_t : \Pi \mid D) \ge \frac{1}{t} \sum_{i=1}^t \|\psi(\phi) - \psi(\{i\})\|$$

Note: bit-vectors of length $t \equiv$ subsets of [1..t]

Lemma

Let $t = 2^k$.

$$\sum_{i=1}^t \left\| \psi(\emptyset) - \psi(\{i\}) \right\| \ge \left\| \psi(\emptyset) - \psi([1..t]) \right\| \cdot \prod_{\ell=1}^k \left(1 - \frac{1}{2^\ell} \right),$$

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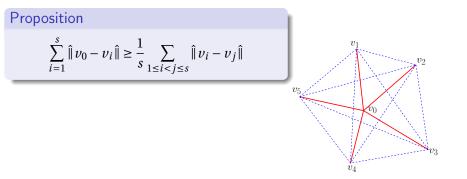
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•
$$\|\psi(\phi) - \psi([1..t])\| = \Omega(1)$$
 (soundness)
• $\prod_{\ell=1}^{k} (1 - \frac{1}{2^{\ell}}) = 0.288788...$ as $k \to \infty$ (digital search tree constant)
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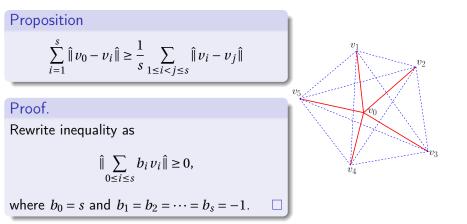
Star Property—a Negative-Type Inequality



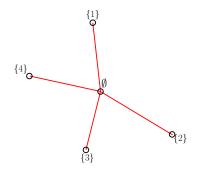
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Star Property—a Negative-Type Inequality



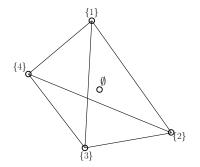
$$\sum_{i=1}^{2^k} \|\psi(\phi) - \psi(\{i\})\|$$



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$$\begin{split} &\sum_{i=1}^{2^{k}} \|\psi(\phi) - \psi(\{i\})\| \\ &\geq \frac{1}{2^{k}} \sum_{1 \leq i < j \leq 2^{k}} \|\psi(\{i\}) - \psi(\{j\})\| \end{split}$$

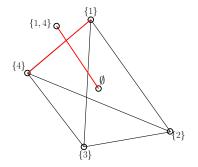


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(Star property)

$$\sum_{i=1}^{2^{k}} \|\psi(\phi) - \psi(\{i\})\|$$

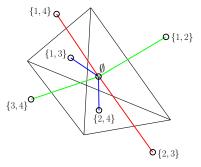
$$\geq \frac{1}{2^{k}} \sum_{1 \le i < j \le 2^{k}} \|\psi(\{i\}) - \psi(\{j\})\|$$



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 $\left(\mathsf{Cut-and-paste} \ [\mathsf{BJKS}]: \ \|\psi(A) - \psi(B)\| = \|\psi(A \cap B) - \psi(A \cup B)\|\right)$

$$\begin{split} &\sum_{i=1}^{2^{k}} \|\psi(\emptyset) - \psi(\{i\})\| \\ &\geq \frac{1}{2^{k}} \sum_{1 \leq i < j \leq 2^{k}} \|\psi(\{i\}) - \psi(\{j\})\| \\ &= \frac{1}{2^{k}} \sum_{1 \leq i < j \leq 2^{k}} \|\psi(\emptyset) - \psi(\{i, j\})\| \end{split}$$



 $\left(\mathsf{Cut-and-paste} \ [\mathsf{BJKS}]: \ \|\psi(A) - \psi(B)\| = \|\psi(A \cap B) - \psi(A \cup B)\|\right)$

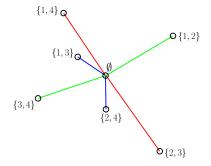
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 December 19, 2009

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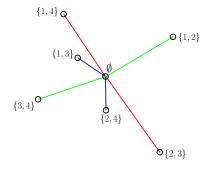
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(Induction)

Part IV

Future Directions

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- The techniques exploit the geometry of Hellinger distance and communication protocols
- Applications:
 - Lower bounds for data streams [Jayram and Woodruff]
 - Sketching edit distance [Andoni, Jayram and Patrascu]
 - Communication complexity of functions in AC⁰ (aka And-Or trees) [Jayram,Kopparty and Raghavendra]
- What about number-on-forehead?

- The techniques exploit the geometry of Hellinger distance and communication protocols
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- What about number-on-forehead?
 - Consider multi-party set-disjointness
 - Best bounds of the form $\Omega(n^{1/k}/f(k))$ [Lee and Shraibman; Chattopadhyay and Ada; Beame and Huynh-Ngoc]
 - Can one hope to prove a $\Omega(n/f(k))$ bound?

- Define information cost as $\sum_{i} I(X_i : \Pi \mid X_{-i}, R_{-i}, D)$
- Direct sum works with this definition!
- Big unknown: the information complexity of And?

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Questions/Comments?

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